



UNIVERSITY OF NIŠ

Course Unit Descriptor

Faculty

Faculty of Mechanical Engineering

GENERAL INFORMATION

Study Program	Mechanical Engineering
Study Module (if applicable)	Mechatronics and Control
Course Title	Basics of Mechatronics Systems Modelling
Level of Study	<input checked="" type="checkbox"/> Bachelor <input type="checkbox"/> Master's <input type="checkbox"/> Doctoral
Type of Course	<input type="checkbox"/> Obligatory <input checked="" type="checkbox"/> Elective
Semester	<input checked="" type="checkbox"/> Autumn <input type="checkbox"/> Spring
Year of Study	IV
Number of ECTS Allocated	6
Name of Lecturer/Lecturers	Miloš S. Milošević
Teaching Mode	<input checked="" type="checkbox"/> Lectures <input checked="" type="checkbox"/> Group tutorials <input checked="" type="checkbox"/> Individual tutorials <input checked="" type="checkbox"/> Laboratory work <input checked="" type="checkbox"/> Project work <input checked="" type="checkbox"/> Seminar <input type="checkbox"/> Distance learning <input type="checkbox"/> Blended learning <input type="checkbox"/> Other

Purpose and Overview (max. 5 sentences)

Introduction to modeling and simulation. The use of modern software packages for physical modeling and simulation of the dynamics of multi bodies with integration with software for computer control. Verification of the model and its use on practical examples of modeling and simulation of complex mechatronic systems. Modeling of complex mechatronic systems in which the functions are based on coupled effects of different physical areas. Identifying influential parameters and adjust complex mechatronic systems thus ensuring their proper function.

Syllabus (brief outline and summary of topics, max. 10 sentences)

Introduction to modeling. Objectives. Motivation. The application of modeling and simulation in the identification, design and optimization of mechatronic systems. Principles and methods of modeling and simulation. Model classification. Simplifications. Faults. Modern software packages for modeling multi bodies. Comparative analysis of the features, benefits and disadvantages. The virtual modeling of mechatronic systems. Modelling of physical models. Basics of modeling in modern software packages. Forming models of mechatronic systems using a computer. Parametric models. Two-dimensional and three-dimensional models. Modeling components and complex mechatronic systems. Integration of models of various nature. Examples of modeling components of mechatronic systems, complex mechatronic systems.

Language of Instruction

- Serbian (complete course) English (complete course) Other _____ (complete course)
 Serbian with English mentoring Serbian with other mentoring _____

Assessment Methods and Criteria

Pre exam Duties	Points	Final Exam	Points
Activity During Lectures	10	Written Examination	0
Practical Teaching	10	Oral Examination	20
Teaching Colloquia	60	Overall Sum	100

***Final examination mark is formed in accordance with the Institutional documents**